

# Fractional nonlinear degenerate diffusion equations on bounded domains

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## References:

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*Preprint (2013)*. <http://arxiv.org/abs/1311.6997>
- [BV2] M. B., J. L. VÁZQUEZ, Nonlinear Degenerate Diffusion Equations on bounded domains with Restricted Fractional Laplacian.  
*In Preparation (2014)*.
- [BSV] M. B., Y. SIRE, J. L. VÁZQUEZ, Existence, Uniqueness and Asymptotic behaviour for fractional porous medium equations on bounded domains.  
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## Outline of the talk

- **The setup of the problem and first pointwise estimates**
- **Upper Estimates**
- **Lower bounds and Harnack inequalities**
- **Existence, uniqueness and asymptotic behaviour of solutions**

## The setup of the problem and first pointwise estimates

- **Introduction**
- **About the operator  $\mathcal{L}$**
- **About the inverse operator  $\mathcal{L}^{-1}$**
- **The “dual” formulation of the problem**
- **Monotonicity for the nonlinear flow**
- **The fundamental pointwise estimates**

## Homogeneous Dirichlet Problem for Fractional Nonlinear Degenerate Diffusion Equations

$$(HDP) \quad \begin{cases} u_t + \mathcal{L}F(u) = 0, & \text{in } (0, +\infty) \times \Omega \\ u(0, x) = u_0(x), & \text{in } \Omega \\ u(t, x) = 0, & \text{on the lateral boundary.} \end{cases}$$

where:

- $\Omega \subset \mathbb{R}^N$  is a bounded domain with smooth boundary and  $N \geq 1$ .
- The linear operator  $\mathcal{L}$  will be a fractional Laplacian on domains,

$$\mathcal{L} = (-\Delta_\Omega)^s, \quad \text{with } 0 < s \leq 1.$$

Indeed, a wider class of linear (fractional) operators can be treated.

- The nonlinearity is typically  $F(u) = |u|^{m-1}u$ , with  $m > 1$ .  
We deal with Degenerate diffusion of Porous Medium type.  
More general classes of “degenerate” nonlinearities  $F$  are allowed.
- The homogeneous boundary condition is posed on the lateral boundary, which may take different forms, depending on the particular choice of the operator  $\mathcal{L}$ .

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## About the operator $\mathcal{L}$

### Reminder about the fractional Laplacian operator on $\mathbb{R}^N$

We have several equivalent definitions for  $(-\Delta_{\mathbb{R}^N})^s$ :

- 1 By means of **Fourier Transform**,

$$((-\Delta_{\mathbb{R}^N})^s f)^\wedge(\xi) = |\xi|^{2s} \hat{f}(\xi).$$

This formula can be used for positive and negative values of  $s$ .

- 2 By means of an **Hypersingular Kernel**:  
if  $0 < s < 1$ , we can use the representation

$$(-\Delta_{\mathbb{R}^N})^s g(x) = c_{N,s} \text{P.V.} \int_{\mathbb{R}^N} \frac{g(x) - g(z)}{|x - z|^{N+2s}} dz,$$

where  $c_{N,s} > 0$  is a normalization constant.

- 3 **Spectral definition**, in terms of the heat semigroup associated to the standard Laplacian operator:

$$(-\Delta_{\mathbb{R}^N})^s g(x) = \frac{1}{\Gamma(-s)} \int_0^\infty \left( e^{t\Delta_{\mathbb{R}^N}} g(x) - g(x) \right) \frac{dt}{t^{1+s}}.$$

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## About the operator $\mathcal{L}$

### Fractional Laplacian operators on bounded domains

There are different definitions for the fractional Laplacian on bounded domains, which turn out to be not equivalent.

#### The Spectral Fractional Laplacian operator (SFL)

$$(-\Delta_\Omega)^s g(x) = \sum_{j=1}^{\infty} \lambda_j^s \hat{g}_j \phi_j(x) = \frac{1}{\Gamma(-s)} \int_0^\infty \left( e^{t\Delta_\Omega} g(x) - g(x) \right) \frac{dt}{t^{1+s}}.$$

- $\Delta_\Omega$  is the classical Dirichlet Laplacian on the domain  $\Omega$
- EIGENVALUES:  $0 < \lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_j \leq \lambda_{j+1} \leq \dots$  and  $\lambda_j \asymp j^{2/N}$ .
- EIGENFUNCTIONS:  $\phi_j$  are as smooth as the boundary of  $\Omega$  allows, namely when  $\partial\Omega$  is  $C^k$ , then  $\phi_j \in C^\infty(\Omega) \cap C^k(\bar{\Omega})$  for all  $k \in \mathbb{N}$ .

$$\hat{g}_j = \int_\Omega g(x) \phi_j(x) dx, \quad \text{with} \quad \|\phi_j\|_{L^2(\Omega)} = 1.$$

#### Lateral boundary conditions for the SFL

$$u(t, x) = 0, \quad \text{in } (0, \infty) \times \partial\Omega.$$

## About the operator $\mathcal{L}$

## Fractional Laplacian operators on bounded domains

Definition via the hypersingular kernel in  $\mathbb{R}^N$ , “restricted” to functions that are zero outside  $\Omega$ .

### The Restricted Fractional Laplacian operator (RFL)

$$(-\Delta|_{\Omega})^s g(x) = c_{d,s} \text{P.V.} \int_{\mathbb{R}^N} \frac{g(x) - g(z)}{|x - z|^{d+2s}} dz, \quad \text{with } \text{supp}(g) \subseteq \overline{\Omega}.$$

where  $s \in (0, 1)$  and  $c_{N,s} > 0$  is a normalization constant.

- $(-\Delta|_{\Omega})^s$  is a self-adjoint operator on  $L^2(\Omega)$  with a discrete spectrum:
- EIGENVALUES:  $0 < \bar{\lambda}_1 \leq \bar{\lambda}_2 \leq \dots \leq \bar{\lambda}_j \leq \bar{\lambda}_{j+1} \leq \dots$  and  $\bar{\lambda}_j \asymp j^{2s/N}$ .  
Eigenvalues of the RFL are bigger than the ones of SFL:  $\lambda_j^s \leq \bar{\lambda}_j$  for all  $j \in \mathbb{N}$ .
- EIGENFUNCTIONS:  $\bar{\phi}_j$  are the normalized eigenfunctions, are only Hölder continuous up to the boundary, namely  $\bar{\phi}_j \in C^s(\overline{\Omega})$ .

### Lateral boundary conditions for the RFL

$$u(t, x) = 0, \quad \text{in } (0, \infty) \times (\mathbb{R}^N \setminus \Omega).$$

**Remark.** Both for the SFL and the RFL there is another possible definition using the so-called Caffarelli-Silvestre extension.

## Reminder about Green functions

**Notation.** Let  $(\lambda_k, \Phi_k)$  be the eigenvalues and eigenfunctions of  $\mathcal{L}$ . Recall that:

$$\Phi_1(x) \asymp \text{dist}(x, \partial\Omega)^\gamma \quad \text{with } \gamma = 1 \text{ for the SFL and } \gamma = s \text{ for the RFL.}$$

The inverse  $\mathcal{L}^{-1}$  has a symmetric kernel  $G_\Omega(x, y)$ , which is the Green function:

$$\mathcal{L}^{-1}f(x_0) := \sum_{k=1}^{+\infty} \lambda_k^{-1} \hat{f}_k \Phi_k(x_0) = \int_{\Omega} G_\Omega(x, x_0) f(x) \, dx.$$

When dealing with the SFL or RFL, it is well-known that the Green function satisfy the following estimates for all  $x, x_0 \in \Omega$ :

$$\text{(Type I)} \quad 0 \leq G_\Omega(x, x_0) \leq \frac{c_{1,\Omega}}{|x - x_0|^{N-2s}} \sim G_{\mathbb{R}^N}(x, x_0),$$

(Type II)

$$c_{0,\Omega} \Phi_1(x) \Phi_1(x_0) \leq G_\Omega(x, x_0) \leq \frac{c_{1,\Omega}}{|x - x_0|^{N-2s}} \left( \frac{\Phi_1(x)}{|x - x_0|^\gamma} \wedge 1 \right) \left( \frac{\Phi_1(x_0)}{|x - x_0|^\gamma} \wedge 1 \right).$$

with  $\gamma = 1$  for the SFL and  $\gamma = s$  for the RFL.

It is hopeless to resume the huge literature about estimates on Green functions.

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with  $\gamma = 1$  for the SFL and  $\gamma = s$  for the RFL.

It is hopeless to resume the huge literature about estimates on Green functions.

## The “dual” formulation of the problem

Recall the homogeneous Dirichlet problem:

$$(HDP) \quad \begin{cases} \partial_t u = -\mathcal{L}F(u), & \text{in } (0, +\infty) \times \Omega \\ u(0, x) = u_0(x), & \text{in } \Omega \\ u(t, x) = 0, & \text{on the lateral boundary.} \end{cases}$$

We can formulate a “dual problem”, using the inverse  $\mathcal{L}^{-1}$  as follows

$$\partial_t U = -F(u),$$

where

$$U(t, x) := \mathcal{L}^{-1}[u(t, \cdot)](x) = \int_{\Omega} \mathbb{K}(x, y) u(t, y) dy.$$

This formulation encodes the lateral boundary conditions in the inverse operator  $\mathcal{L}^{-1}$ .

**Remark.** This formulation has been used before by Pierre, Vázquez [...] to prove (in the  $\mathbb{R}^N$  case) uniqueness of the “fundamental solution”, i.e. the solution corresponding to  $u_0 = \delta_{x_0}$ , known as the Barenblatt solution.



## The “dual” formulation of the problem

### Definition of Weak Dual solutions

Recall that

$$\|f\|_{L^1_{\Phi_1}(\Omega)} = \int_{\Omega} f(x)\Phi_1(x) dx, \quad \text{and} \quad L^1_{\Phi_1}(\Omega) := \{f : \Omega \rightarrow \mathbb{R} \mid \|f\|_{L^1_{\Phi_1}(\Omega)} < \infty\}.$$

#### Weak Dual Solutions

A function  $u$  is a *weak dual solution* to the (HDP) if:

$u \in C([0, \infty) : L^1_{\Phi_1}(\Omega))$ ,  $F(u) \in L^1((0, T) : L^1_{\Phi_1}(\Omega))$ , and moreover  $u(0, x) = u_0 \in L^1_{\Phi_1}(\Omega)$ .

The following identity holds for every  $\psi$  with  $\psi/\Phi_1 \in C_c^1((0, T) : L^\infty(\Omega))$ :

$$\int_0^T \int_{\Omega} \mathcal{L}^{-1}(u) \frac{\partial \psi}{\partial t} dx dt - \int_0^\infty \int_{\Omega} F(u) \psi dx dt = 0.$$

We will need a special class of weak dual solutions:

#### The class $\mathcal{S}_p$ of weak dual solutions

We consider a class  $\mathcal{S}_p$  of nonnegative weak dual solutions  $u$  to the (HDP) with initial data in  $u_0 \in L^1_{\Phi_1}(\Omega)$ , such that (i) the map  $u_0 \mapsto u(t)$  is order preserving in  $L^1_{\Phi_1}(\Omega)$ ; (ii) for all  $t > 0$  we have  $u(t) \in L^p(\Omega)$  for some  $p \geq 1$ .

## Monotonicity estimates for powers

The nonlinear flow has a very important monotonicity property, which is related to the  $m$ -homogeneity of the equation. Benilan and Crandall proved the following estimates for the case  $F(u) = u^m$ , with  $m > 1$ .

### Monotonicity estimates

Every mild solution  $u \geq 0$  corresponding to an initial datum  $u_0 \in L^1(\Omega)$ , satisfies the following differential estimate

$$u_t \geq -\frac{u}{(m-1)t} \quad \text{in the sense of distributions in } (0, \infty) \times \Omega.$$

Alternatively, we have the following monotonicity in time, namely the function

$$t \mapsto t^{\frac{1}{m-1}} u(t, x) \quad \text{is nondecreasing in } t > 0 \text{ for a.e. } x \in \Omega.$$

## The fundamental pointwise estimates I: the pure power case

### Theorem (M.B. and J. L. Vázquez, 2013)

Let  $0 \leq u \in \mathcal{S}_p$ , with  $p > N/2s$ . Then,

$$\int_{\Omega} u(t, x) G_{\Omega}(x, x_0) dx \leq \int_{\Omega} u_0(x) G_{\Omega}(x, x_0) dx \quad \text{for all } t > 0.$$

Moreover, for almost every  $0 \leq t_0 \leq t_1$  and almost every  $x_0 \in \Omega$ , we have

$$\frac{t_0^{\frac{m}{m-1}}}{t_1^{\frac{m}{m-1}}} (t_1 - t_0) u^m(t_0, x_0) \leq \int_{\Omega} [u(t_0, x) - u(t_1, x)] G_{\Omega}(x, x_0) dx \leq c_m \frac{t_1^{\frac{m}{m-1}}}{t_0^{\frac{1}{m-1}}} u^m(t_1, x_0)$$

with  $c_m = m - 1$

**Remark.** As a consequence of the above inequality and Hölder inequality, we have that  $\mathcal{S}_p = \mathcal{S}_{\infty}$ , when  $p > N/2s$ .

▸ A more general setup

## Upper Estimates

- **Absolute upper bounds**
  - Absolute bounds
  - Sharp upper boundary behaviour
- **Smoothing Effects**
  - $L^1$ - $L^\infty$  Smoothing Effects
  - $L^1_{\Phi_1}$ - $L^\infty$  Smoothing Effects
  - Backward in time Smoothing effects

**Theorem. (Absolute upper estimate and boundary behaviour)**

(M.B. &amp; J. L. Vázquez, 2013)

Let  $u$  be a weak dual solution. Then, there exists universal constants  $K_1, K_2 > 0$  such that the following estimates hold true: Type I estimates imply

$$\|u(t)\|_{L^\infty(\Omega)} \leq \frac{K_1}{t^{\frac{1}{m-1}}}, \quad \text{for all } t > 0.$$

Moreover, Type II estimates imply

$$u(t, x) \leq K_2 \frac{\Phi_1(x)^{\frac{1}{m}}}{t^{\frac{1}{m-1}}} \quad \text{for all } t > 0 \text{ and } x \in \Omega.$$

**Remark.**

- This is a very strong regularization *independent* of the initial datum  $u_0$ .
- The boundary estimates are sharp, since we will obtain lower bounds with matching powers.
- These bounds give a sharp time decay for the solution, but only for large times, say  $t \geq 1$ . For small times we will obtain a better time decay when  $0 < t < 1$ , in the form of smoothing effects

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## Sketch of the proof of Absolute Bounds

- STEP 1. *First upper estimates.* Recall the pointwise estimate:

$$\left(\frac{t_0}{t_1}\right)^{\frac{m}{m-1}} (t_1 - t_0) u^m(t_0, x_0) \leq \int_{\Omega} u(t_0, x) G_{\Omega}(x, x_0) dx - \int_{\Omega} u(t_1, x) G_{\Omega}(x, x_0) dx.$$

for any  $u \in \mathcal{S}_p$ , all  $0 \leq t_0 \leq t_1$  and all  $x_0 \in \Omega$ . Choose  $t_1 = 2t_0$  to get

$$(*) \quad u^m(t_0, x_0) \leq \frac{2^{\frac{m}{m-1}}}{t_0} \int_{\Omega} u(t_0, x) G_{\Omega}(x, x_0) dx.$$

Recall that  $u \in \mathcal{S}_p$  with  $p > N/(2s)$ , means  $u(t) \in L^p(\Omega)$  for all  $t > 0$ , so that:

$$u^m(t_0, x_0) \leq \frac{c_0}{t_0} \int_{\Omega} u(t_0, x) G_{\Omega}(x, x_0) dx \leq \frac{c_0}{t_0} \|u(t_0)\|_{L^p(\Omega)} \|G_{\Omega}(\cdot, x_0)\|_{L^q(\Omega)} < +\infty$$

since  $G_{\Omega}(\cdot, x_0) \in L^q(\Omega)$  for all  $0 < q < N/(N - 2s)$ , so that  $u(t_0) \in L^{\infty}(\Omega)$  for all  $t_0 > 0$ .

- STEP 2. Let us estimate the r.h.s. of (\*) as follows:

$$u^m(t_0, x_0) \leq \frac{c_0}{t_0} \int_{\Omega} u(t_0, x) G_{\Omega}(x, x_0) dx \leq \|u(t_0)\|_{L^{\infty}(\Omega)} \frac{c_0}{t_0} \int_{\Omega} G_{\Omega}(x, x_0) dx.$$

Taking the **supremum over  $x_0 \in \Omega$**  of both sides, we get:

$$\|u(t_0)\|_{L^{\infty}(\Omega)}^{m-1} \leq \frac{c_0}{t_0} \sup_{x_0 \in \Omega} \int_{\Omega} G_{\Omega}(x, x_0) dx \leq \frac{K_1^{m-1}}{t_0} \quad \square$$

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Define the exponents:

$$\vartheta_{1,\gamma} = \frac{1}{2s + (N + \gamma)(m - 1)} \quad \text{and} \quad \vartheta_1 = \vartheta_{1,0} = \frac{1}{2s + N(m - 1)}$$

**Theorem. (Smoothing effects)** (M.B. & J. L. Vázquez, 2013)

There exist universal constants  $K_3, K_4 > 0$  such that the following estimates hold.

$L^1$ - $L^\infty$  SMOOTHING EFFECT: are consequence of Type I bounds

$$\|u(t)\|_{L^\infty(\Omega)} \leq \frac{K_3}{t^{N\vartheta_1}} \|u(t)\|_{L^1(\Omega)}^{2s\vartheta_1} \leq \frac{K_3}{t^{N\vartheta_1}} \|u_0\|_{L^1(\Omega)}^{2s\vartheta_1} \quad \text{for all } t > 0.$$

$L^1_{\Phi_1}$ - $L^\infty$  SMOOTHING EFFECT: are consequence of Type II bounds; for all  $t > 0$ :

$$\|u(t)\|_{L^\infty(\Omega)} \leq \frac{K_4}{t^{(N+\gamma)\vartheta_{1,\gamma}}} \|u(t)\|_{L^1_{\Phi_1}(\Omega)}^{2s\vartheta_{1,\gamma}} \leq \frac{K_4}{t^{(N+\gamma)\vartheta_{1,\gamma}}} \|u_0\|_{L^1_{\Phi_1}(\Omega)}^{2s\vartheta_{1,\gamma}}.$$

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$$(N + \gamma)\vartheta_{1,\gamma} = \frac{N + \gamma}{2 + (N + \gamma)(m - 1)} < \frac{1}{m - 1}.$$

Define the exponents:

$$\vartheta_{1,\gamma} = \frac{1}{2s + (N + \gamma)(m - 1)} \quad \text{and} \quad \vartheta_1 = \vartheta_{1,0} = \frac{1}{2s + N(m - 1)}$$

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**Theorem. (Backward Smoothing effects)** (M.B. & J. L. Vázquez, 2013)

There exists a universal constant  $K_4 > 0$  such that for all  $t, h > 0$

$$\|u(t)\|_{L^\infty(\Omega)} \leq \frac{K_4}{t^{(d+\gamma)\vartheta_{1,\gamma}}} \left(1 \vee \frac{h}{t}\right)^{\frac{2s\vartheta_{1,\gamma}}{m-1}} \|u(t+h)\|_{L^1_{\Phi_1}(\Omega)}^{2s\vartheta_{1,\gamma}}.$$

*Proof.* By the monotonicity estimates, the function  $u(x, t)t^{1/(m-1)}$  is non-decreasing in time for fixed  $x$ , therefore using the smoothing effect, we get for all  $t_1 \geq t$ :

$$\begin{aligned} \|u(t)\|_{L^\infty(\Omega)} &\leq \frac{K_4}{t^{(N+1)\vartheta_{1,\gamma}}} \left( \int_{\Omega} u(t, x) \Phi_1(x) \, dx \right)^{2s\vartheta_{1,\gamma}} \\ &\leq \frac{K_4}{t^{(N+1)\vartheta_{1,\gamma}}} \left( \frac{t_1^{-\frac{1}{m-1}}}{t^{-\frac{1}{m-1}}} \int_{\Omega} u(t_1, x) \Phi_1(x) \, dx \right)^{2s\vartheta_{1,\gamma}} \end{aligned}$$

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## Lower bounds and Harnack inequalities

- **Quantitative positivity estimates**
- **Weighted  $L^1_{\Phi_1}$  estimates**
- **Harnack inequalities**
- **Estimates for Elliptic equations**

**Theorem. (Lower absolute and boundary estimates)**

(M.B. &amp; J. L. Vázquez, 2013)

Let let  $m > 1$  and let  $u \geq 0$  be a weak dual solution to the Dirichlet problem (1), corresponding to the initial datum  $0 \leq u_0 \in L^1_{\Phi_1}(\Omega)$ . Then, there exist constants  $L_0(\Omega), L_1(\Omega) > 0$ , so that, setting

$$t_* = \frac{L_0(\Omega)}{\left(\int_{\Omega} u_0 \Phi_1 \, dx\right)^{m-1}},$$

we have that for all  $t \geq t_*$  and all  $x_0 \in \Omega$ , the following inequality holds:

$$u(t, x_0) \geq L_1(\Omega) \frac{\Phi_1(x_0)^{\frac{1}{m}}}{t^{\frac{1}{m-1}}}.$$

The constants  $L_0(\Omega), L_1(\Omega) > 0$ , depend on  $N, m, s$  and on  $\Omega$ , but not on  $u$  (or any norm of  $u$ ); they have an explicit form.

## Remarks.

- Recall that  $\Phi_1$  is the first eigenfunction of  $\mathcal{L}$  and satisfies:

$$\Phi_1(x) \asymp \text{dist}(x, \partial\Omega)^\gamma \wedge 1 \quad \text{for all } x \in \Omega.$$

Therefore, the lower boundary behaviour of  $u(t, \cdot)$  is:

$$u(t, x) \geq \frac{L_1}{t_0^{\frac{1}{m-1}}} (\text{dist}(x_0, \partial\Omega)^{\frac{\gamma}{m}} \wedge 1), \quad \text{for all } t_0 \geq t_* \geq 0 \text{ and } x_0 \in \Omega.$$

- This boundary behaviour is sharp because we have upper bounds with matching powers of  $\Phi_1$ .
- $t_*$  is an estimate the time that it takes to fill the hole: if  $u_0$  is concentrated close to the border (leaves an hole in the middle of  $\Omega$ ), then  $\int_{\Omega} u_0 \Phi_1 \, dx$  is small, therefore  $t_*$  becomes very large, therefore it takes a lot of time to fill the hole.
- These estimates can also be rewritten as Aronson-Caffarelli type estimates:

$$\text{either } t \leq t_* = \frac{L_0}{\left(\int_{\Omega} u_0 \Phi_1 \, dx\right)^{m-1}}, \quad \text{or } u(t, x_0) \geq L_1 \frac{\Phi_1(x_0)^{\frac{1}{m}}}{t^{\frac{1}{m-1}}} \quad \forall t \geq t_*,$$

which gives, for all  $t \geq 0$  and all  $x_0 \in \Omega$ :

$$u(t, x_0) \geq \frac{L_1 \Phi_1(x_0)^{\frac{1}{m}}}{t^{\frac{1}{m-1}}} \left[ 1 - \left( \frac{t_*}{t} \right)^{\frac{1}{m-1}} \right].$$

- Open problem:* find precise lower bounds for small times,  $0 < t < t_*$ .

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**Proposition. (Weighted  $L^1$ -estimates)**

Under the current assumptions on  $m$  and  $u$ , the integral  $\int_{\Omega} u(t, x) \Phi_1(x) dx$  is monotonically non-increasing in time and for all  $0 \leq \tau_0 \leq \tau, t < +\infty$  we have

$$\int_{\Omega} u(\tau, x) \Phi_1(x) dx \leq \int_{\Omega} u(t, x) \Phi_1(x) dx + K_5 |t - \tau|^{2s\vartheta_{1,\gamma}} \left( \int_{\Omega} u(\tau_0) \Phi_1 dx \right)^{2s(m-1)\vartheta_{1,\gamma} + 1}$$

where  $K_5 := \lambda_1 K_4 / (2s\vartheta_{1,\gamma})$  and  $K_4 > 0$  is the constant in the smoothing effects.

**Remark.** Notice that, contrary to the usual monotonicity, we can allow  $\tau \leq t$ .

**Proposition. (Almost  $L^1_{\Phi_1}$ -contractivity)**

For ordered solutions  $u \geq v$ , we have that for all  $0 \leq \tau_0 \leq \tau, t < +\infty$

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**Corollary. (Backward in time  $L^1_{\Phi_1}$  lower bounds)**

For all

$$0 \leq \tau_0 \leq t \leq \tau_0 + \frac{1}{K_6 \left( \int_{\Omega} u(\tau_0) \Phi_1 \, dx \right)^{m-1}}$$

we have

$$\frac{1}{2} \int_{\Omega} u(\tau_0, x) \Phi_1(x) \, dx \leq \int_{\Omega} u(t, x) \Phi_1(x) \, dx.$$

where  $K_6 = (2K_5)^{1/(2s\vartheta_{1,1})} > 0$  and  $K_5$  is as in the above Proposition.**Corollary. (Absolute lower bounds for the  $L^1_{\Phi_1}$  norm)**The choice  $\tau_0 = 0$  and  $t = K_6^{-1} \left( \int_{\Omega} u_0 \Phi_1 \, dx \right)^{-(m-1)}$  gives

$$t^{\frac{1}{m-1}} \int_{\Omega} u(t, x) \Phi_1(x) \, dx \geq \frac{t^{\frac{1}{m-1}}}{2} \int_{\Omega} u_0(x) \Phi_1(x) \, dx = \frac{1}{2K_6^{m-1}}$$

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**Theorem. (Global Harnack Principle)** (M.B. & J. L. Vázquez, 2013)

There exist universal constants  $H_0, H_1, L_0 > 0$  such that setting

$$t_* = \frac{L_0}{\left(\int_{\Omega} u_0 \Phi_1 \, dx\right)^{m-1}},$$

we have that for all  $t \geq t_*$  and all  $x \in \Omega$ , the following inequality holds:

$$H_0 \frac{\Phi_1(x)^{\frac{1}{m}}}{t^{\frac{1}{m-1}}} \leq u(t, x) \leq H_1 \frac{\Phi_1(x)^{\frac{1}{m}}}{t^{\frac{1}{m-1}}}$$

Recall that  $\Phi_1$  is the first eigenfunction of  $\mathcal{L}$ .

**Remarks.**

- This inequality implies local Harnack inequalities of elliptic type
- As a corollary we get the sharp asymptotic behaviour (Part 4)

Solutions  $u$  to the parabolic problem inherit the Harnack inequality for  $\Phi_1$ :

$$\sup_{x \in B_R(x_0)} \Phi_1(x) \leq \mathcal{H} \inf_{x \in B_R(x_0)} \Phi_1(x) \quad \forall B_R(x_0) \in \Omega.$$

The constant  $\mathcal{H} > 0$  is universal (and explicit at least when  $s = 1$ , cf. [BGV-2012]).

### Theorem. (Local Harnack Inequalities of Elliptic Type)

(M.B. & J. L. Vázquez, 2013)

There exist universal constants  $H_0, H_1, L_0 > 0$  such that setting  $t_* = L_0 \|u_0\|_{L^1_{\Phi_1}(\Omega)}^{-(m-1)}$ , we have that for all  $t \geq t_*$  and all  $B_R(x_0) \in \Omega$ , the following inequality holds:

$$\sup_{x \in B_R(x_0)} u(t, x) \leq \frac{H_1 \mathcal{H}_m^{\frac{1}{m}}}{H_0} \inf_{x \in B_R(x_0)} u(t, x)$$

### Corollary. (Local Harnack Inequalities of Backward Type)

Under the running assumptions, for all  $t \geq t_*$  and all  $B_R(x_0) \in \Omega$ , we have:

$$\sup_{x \in B_R(x_0)} u(t, x) \leq 2 \frac{H_1 \mathcal{H}_m^{\frac{1}{m}}}{H_0} \inf_{x \in B_R(x_0)} u(t + h, x) \quad \text{for all } 0 \leq h \leq t_*.$$



We consider the homogeneous Dirichlet problem

$$(1) \quad \begin{cases} \mathcal{L}(V^m) = \lambda V, & \text{in } \Omega, \\ V = 0, & \text{on } \partial\Omega, \end{cases}$$

under the running assumptions on  $\Omega, m, s, N, \mathcal{L}$ .

### Theorem. (Bounds and boundary behaviour for the elliptic problem)

Let  $V \geq 0$  be a very weak solution to the Dirichlet Problem (1), then there exist universal positive constants  $h_0$  and  $h_1$  such that the following estimates hold true for all  $x_0 \in \Omega$ :

$$h_0 \|V\|_{L^1_{\Phi_1}} \Phi_1(x_0) \leq V^m(x_0) \leq h_1 \Phi_1(x_0),$$

where  $h_1 = c_{5,\Omega} \lambda^{1/(m-1)}$  and  $h_0 = c_{0,\Omega} \lambda$ , with  $c_{5,\Omega}$  given in Lemma “Integral Green function estimates II” and  $c_{0,\Omega}$  is the constant in the Type II lower estimates.

## Existence, uniqueness and asymptotic behaviour of solutions

- **Existence and uniqueness theory**
  - Existence and uniqueness theory in  $L^1_{\Phi_1}$
  - **Reminder about fractional Sobolev spaces on bounded domains**
  - Existence and uniqueness theory in  $H^*(\Omega)$
  - Existence for the elliptic problem via parabolic methods
- **Asymptotic behaviour of nonnegative solutions**
  - The rescaled flow and stationary solutions
  - Convergence to the stationary profile
  - The Friendly Giant and convergence with optimal rate

### Theorem. (Existence and Uniqueness in $L^1_{\Phi_1}$ ) (M.B. & J. L. Vázquez, 2013-14)

For every nonnegative  $u_0 \in L^1_{\Phi_1}(\Omega)$  there exists a unique minimal weak dual solution to the Dirichlet problem:

$$(HDP) \quad \begin{cases} u_t + \mathcal{L}F(u) = 0, & \text{in } (0, +\infty) \times \Omega \\ u(0, x) = u_0(x), & \text{in } \Omega \\ u(t, x) = 0, & \text{on the lateral boundary.} \end{cases}$$

Such a solution is obtained as the monotone limit of the semigroup solutions that exist and are unique when the initial data are in  $L^1(\Omega)$ . The minimal weak dual solution is continuous in the weighted space  $u \in C([0, \infty) : L^1_{\Phi_1}(\Omega))$ . Moreover, it belongs to the class  $\mathcal{S}$ .

This is a consequence of the upper estimates and of the almost-contractivity in  $L^1_{\Phi_1}(\Omega)$ .

We now pass to a more general framework, and we prove existence and uniqueness.

## Consider the Problem

$$\begin{cases} u_t + \mathcal{L}(\varphi(u)) = 0 & \text{in } (0, +\infty) \times \Omega \\ u(0, x) = u_0(x) & \text{in } \Omega \\ u(t, x) = 0 & \text{on } (0, +\infty) \times \Gamma \end{cases}$$

$\varphi : \mathbb{R} \rightarrow \mathbb{R}$  is a continuous, smooth and increasing function.

Assume moreover that  $\varphi' > 0$ ,  $\varphi(\pm\infty) = \pm\infty$  and  $\varphi(0) = 0$ .

The leading example is  $\varphi(u) = |u|^{m-1}u$  with  $m > 0$ .

$\mathcal{L}$  is a linear operator with eigenelements  $(\lambda_{k,s}, \phi_{k,s})$ .

We study the above problem in the framework of fractional Sobolev spaces:

$$H(\Omega) = \left\{ u = \sum_{k=1}^{\infty} u_k \phi_{k,s} \in L^2(\Omega) : \|u\|_H^2 = \sum_{k=1}^{\infty} \lambda_{k,s} |u_k|^2 < +\infty \right\} \subset L^2(\Omega)$$

and let  $H^*(\Omega)$  be the topological dual of  $H(\Omega)$ .

Under some assumption on  $\mathcal{L}$ , essentially that  $\lambda_k \leq C^k$  for some  $C > 0$ ,

we can identify  $H(\Omega)$  in terms of more familiar spaces:

$$H(\Omega) = \begin{cases} H_0^s(\Omega), & \text{if } \frac{1}{2} < s \leq 1, \\ H_{00}^{1/2}(\Omega), & \text{if } s = \frac{1}{2}, \\ H^s(\Omega), & \text{if } 0 < s < \frac{1}{2}. \end{cases}$$

There is another possible characterization of the space  $H(\Omega)$ ,

$$H(\Omega) = \dot{H}^s(\bar{\Omega}) = \{ u \in H^s(\mathbb{R}^d) \mid \text{supp}(u) \subset \bar{\Omega} \}$$

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$$H(\Omega) = \left\{ u = \sum_{k=1}^{\infty} u_k \phi_{k,s} \in L^2(\Omega) : \|u\|_H^2 = \sum_{k=1}^{\infty} \lambda_{s,k} |u_k|^2 < +\infty \right\} \subset L^2(\Omega)$$

and let  $H^*(\Omega)$  be the topological dual of  $H(\Omega)$ .

Under some assumption on  $\mathcal{L}$ , essentially that  $\lambda_k \leq C^k$  for some  $C > 0$ ,

we can identify  $H(\Omega)$  in terms of more familiar spaces:

$$H(\Omega) = \begin{cases} H_0^s(\Omega), & \text{if } \frac{1}{2} < s \leq 1, \\ H_{00}^{1/2}(\Omega), & \text{if } s = \frac{1}{2}, \\ H^s(\Omega), & \text{if } 0 < s < \frac{1}{2}. \end{cases}$$

There is another possible characterization of the space  $H(\Omega)$ ,

$$H(\Omega) = \dot{H}^s(\bar{\Omega}) = \{ u \in H^s(\mathbb{R}^d) \mid \text{supp}(u) \subset \bar{\Omega} \}$$

Consider the Problem

$$\begin{cases} u_t + \mathcal{L}(\varphi(u)) = 0 & \text{in } (0, +\infty) \times \Omega \\ u(0, x) = u_0(x) & \text{in } \Omega \\ u(t, x) = 0 & \text{on } (0, +\infty) \times \Gamma \end{cases}$$

$\varphi : \mathbb{R} \rightarrow \mathbb{R}$  is a continuous, smooth and increasing function.

Assume moreover that  $\varphi' > 0$ ,  $\varphi(\pm\infty) = \pm\infty$  and  $\varphi(0) = 0$ .

The leading example is  $\varphi(u) = |u|^{m-1}u$  with  $m > 0$ .

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**Theorem. (Existence and Uniqueness in  $H^*$ )** (M.B., Y. Sire, J. L. Vázquez, 2014)

For every  $u_0 \in H^*(\Omega)$  there exists a unique solution  $u \in C([0, T] : H^*(\Omega))$  of Problem 2 for every  $T > 0$ , i.e. the solution is global in time. We also have

$${}_t\varphi(u) \in L^\infty(0, T : H^*(\Omega)), \quad {}_t\partial_t u \in L^\infty(0, T : H^*(\Omega)).$$

We also have  ${}_t\varphi(u) \in L^1((0, T) \times \Omega)$ . The solution map  $S_t : u_0 \mapsto u(t)$  defines a semigroup of (non-strict) contractions in  $H^*(\Omega)$ , i. e.,

$$\|u(t) - v(t)\|_{H^*(\Omega)} \leq \|u(0) - v(0)\|_{H^*(\Omega)},$$

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**Remarks.**

- The nonlinearity  $\varphi$  is more general than  $F$ , treated in the previous parts of the talk.
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In the rest of the talk we consider the nonlinearity  $\varphi(u) = |u|^{m-1}u$  with  $m > 1$ .

**Theorem. (Asymptotic behaviour)** (M.B., Y. Sire, J. L. Vázquez, 2014)

There exists a unique nonnegative selfsimilar solution of the Dirichlet Problem (2)

$$U(\tau, x) = \frac{S(x)}{\tau^{\frac{1}{m-1}}},$$

for some bounded function  $S : \Omega \rightarrow \mathbb{R}$ . Let  $u$  be any nonnegative  $H^*$ -solution to the Dirichlet Problem (2), then we have (unless  $u \equiv 0$ )

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such that for all  $t \geq t_0$  we have

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We remark that the constant  $\bar{k} > 0$  only depends on  $m, d, s$ , and  $|\Omega|$  and has explicit expressions given in the proof.

**Remarks.**

- We provide two different proofs of the above result.
- One proof is based on the construction of the so-called Friendly-Giant solution, namely the solution with initial data  $u_0 = +\infty$ , and is based on the Global Harnack Principle of Part 3
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# The End

Daedanhi Gamsahabnida!!!

Grazie Mille!!!

Muchas Gracias!!!

Thank You!!!

Merci Beaucoup!!!

## A general class of linear operators

We may consider any linear operator  $\mathcal{L} : \text{dom}(\mathcal{L}) \subseteq L^1(\Omega) \rightarrow L^1(\Omega)$  which is densely defined and such that

(A1)  $\mathcal{L}$  is  $m$ -accretive on  $L^1(\Omega)$ ,

(A2) If  $0 \leq f \leq 1$  then  $0 \leq e^{-t\mathcal{L}}f \leq 1$ , or equivalently,

(A3) If  $\beta$  is a maximal monotone graph in  $\mathbb{R} \times \mathbb{R}$  with  $0 \in \beta(0)$ ,  $u \in \text{dom}(\mathcal{L})$ ,  $\mathcal{L}u \in L^p(\Omega)$ ,  $1 \leq p \leq \infty$ ,  $v \in L^{p/(p-1)}(\Omega)$ ,  $v(x) \in \beta(u(x))$  a.e., then

$$\int_{\Omega} v(x)\mathcal{L}u(x) \, dx \geq 0$$

### Remarks.

- These assumptions are needed to obtain the existence (and uniqueness) of semi-group (mild) solutions for the nonlinear equation  $u_t = \mathcal{L}F(u)$ , through a variant of the celebrated Crandall-Liggett theorem, as done by Benilan, Crandall and Pierre.
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## Assumptions on the inverse in the general case

We will assume that the operator  $\mathcal{L}$  has an inverse  $\mathcal{L}^{-1}$  with a kernel  $\mathbb{K}$  such that

$$\mathcal{L}^{-1}f(x) = \int_{\Omega} \mathbb{K}(x, y) f(y) \, dy,$$

and that satisfies (one of) the following estimates for some  $\gamma, s \in (0, 1]$  and  $c_{i, \Omega} > 0$

$$(K1) \quad 0 \leq \mathbb{K}(x, y) \leq \frac{c_{1, \Omega}}{|x - y|^{N-2s}}$$

$$(K2) \quad c_{0, \Omega} d(x) d(y) \leq \mathbb{K}(x, y) \leq \frac{c_{1, \Omega}}{|x - y|^{N-2s}} \left( \frac{d(x)^\gamma}{|x - y|^\gamma} \wedge 1 \right) \left( \frac{d(y)^\gamma}{|x - y|^\gamma} \wedge 1 \right)$$

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- It is easy to see that (K2) implies (K3), more precisely, (K2) implies that  $\Phi_1$  behaves like  $\Phi_1 \asymp \text{dist}(\cdot, \partial\Omega)^\gamma$ .
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## Reminder about Mild solutions and their properties

Mild solutions, or semigroup solutions have been obtained by Benilan, Crandall and Pierre via Crandall-Liggett type theorems; the underlying idea is the use of an Implicit Time Discretization (ITD) method: consider the following partition of  $[0, T]$

$$t_k = \frac{k}{n}T, \quad \text{for any } 0 \leq k \leq n, \quad \text{with } t_0 = 0, t_n = T, \quad \text{and} \quad h = t_{k+1} - t_k = \frac{T}{n}.$$

For any  $t \in (0, T)$ , the (unique) semigroup solution  $u(t, \cdot)$  is obtained as the limit in  $L^1(\Omega)$  of the solutions  $u_{k+1}(\cdot) = u(t_{k+1}, \cdot)$  which solve the following elliptic equation ( $u_k$  is the datum, is given by the previous iterative step)

$$h\mathcal{L}F(u_{k+1}) + u_{k+1} = u_k \quad \text{or equivalently} \quad \frac{u_{k+1} - u_k}{h} = -\mathcal{L}F(u_{k+1}).$$

Usually such solutions are difficult to treat since a priori they are merely very weak solutions. We can prove the following result:

### Semigroup solutions with $u_0 \in L^p$ are weak dual solutions

Let  $u$  be the unique mild solution corresponding to the initial datum  $u_0 \in L^p(\Omega)$  with  $p \geq 1$ . Then  $u$  is a weak dual solution and is contained in the class  $\mathcal{S}_p$ .

## Monotonicity estimates in the general case

When the nonlinearity  $F$  is not a pure power, the homogeneity fails, therefore one expects a lack of monotonicity. Crandall and Pierre have proven monotonicity estimate under some assumptions on  $F$ .

(N1) Assume  $F \in C^1(\mathbb{R} \setminus \{0\})$  and  $F' \in \text{Lip}_{\text{loc}}(\mathbb{R} \setminus \{0\})$  and there exists  $\mu_0, \mu_1 \in (0, 1]$  such that

$$\mu_0 \leq \frac{F(r)F''(r)}{[F'(r)]^2} \leq \mu_1 \quad \text{a.e. } r > 0.$$

**Theorem** (M. Crandall and M. Pierre, JFA 1982)

Let  $\mathcal{L}$  satisfy (A1) and (A2) and let  $F$  as satisfy (N1). Then for all nonnegative  $u_0 \in L^1(\Omega)$ , there exists a unique mild solution  $u$  to equation  $u_t + \mathcal{L}F(u) = 0$ , and the function

$$(3) \quad t \mapsto t^{\frac{1}{\mu_0}} F(u(t, x)) \quad \text{is nondecreasing in } t > 0 \text{ for a.e. } x \in \Omega.$$

Moreover, the semigroup is contractive on  $L^1(\Omega)$  and  $u \in C([0, \infty) : L^1(\Omega))$ .

We notice that (3) is a weak formulation of the monotonicity inequality:

$$\partial_t u \geq -\frac{1}{\mu_0 t} \frac{F(u)}{F'(u)}$$

## The fundamental pointwise estimates II: the general case

### Theorem (M.B. and J. L. Vázquez, 2014)

Let  $0 \leq u \in \mathcal{S}_p$ , with  $p > N/2s$ . Then,

$$\int_{\Omega} u(t, x) \mathbb{K}(x, x_0) \, dx \leq \int_{\Omega} u_0(x) \mathbb{K}(x, x_0) \, dx \quad \text{for all } t > 0.$$

Moreover, for almost every  $0 < t_0 \leq t_1 \leq t$  and almost every  $x_0 \in \Omega$ , we have

$$\begin{aligned} \left(\frac{t_0}{t_1}\right)^{\frac{1}{\mu_0}} (t_1 - t_0) F(u(t_0, x_0)) &\leq \int_{\Omega} u(t_0, x) \mathbb{K}(x, x_0) \, dx - \int_{\Omega} u(t_1, x) \mathbb{K}(x, x_0) \, dx \\ &\leq (m_0 - 1) \frac{t^{\frac{1}{\mu_0}}}{t_0^{\frac{1-\mu_0}{\mu_0}}} F(u(t, x_0)). \end{aligned}$$