Nonlocal (and local) nonlinear diffusion equations. Background, analysis, and numerical approximation

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18 June 2019

In collaboration with F. del Teso and E. R. Jakobsen

A talk given at MAFELAP 2019, Brunel University London

Jørgen Endal Nonlocal (and local) nonlinear diffusion equations







F. DEL TESO, JE, E. R. JAKOBSEN. Uniqueness and properties of distributional solutions of nonlocal equations of porous medium type. *Adv. Math.*, 305:78–143, 2017.



F. DEL TESO, JE, E. R. JAKOBSEN. On distributional solutions of local and nonlocal problems of porous medium type. *C. R. Acad. Sci. Paris, Ser. I*, 355(11):1154–1160, 2017.



F. DEL TESO, JE, E. R. JAKOBSEN. Robust numerical methods for nonlocal (and local) equations of porous medium type. Part I: Theory. To appear in *SIAM J. Numer. Anal.*, 2019.



F. DEL TESO, JE, E. R. JAKOBSEN. Robust numerical methods for nonlocal (and local) equations of porous medium type. Part II: Schemes and experiments. *SIAM J. Numer. Anal.*, 56(6):3611–3647, 2018.

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Diffusion is the act of "spreading out" – the movement from areas of high concentration to areas of low concentration.

How do we model this phenomena?

Introduction: Mathematical modelling



Let *u* be some heat density inside a region Ω . The rate of change of the total quantity within Ω equals the negative of the net flux through $\partial\Omega$:

$$\frac{\mathrm{d}}{\mathrm{d}t}\int_{\Omega} u\,\mathrm{d}x = -\int_{\partial\Omega} \mathbf{F}\cdot\mathbf{n}\,\mathrm{d}S = -\int_{\Omega}\mathrm{div}\mathbf{F}\,\mathrm{d}V,$$

or

$$\partial_t u = -\operatorname{div} \mathbf{F},$$

where $\mathbf{F} = \mathbf{F}(u) := -a(u)Du$.

Introduction: Special case when m = 6

•
$$a(u) = u^{m-1}$$
.

It is possible to use

$$\begin{cases} \partial_t u = \Delta[u^6] & \text{ in } \mathbb{R}^N \times (0, T), \\ u(x, 0) = M\delta_0 & \text{ on } \mathbb{R}^N, \end{cases}$$

to describe the propagation of heat immediately after a nuclear explosion.





G. I. BARENBLATT. Scaling, self-similarity, and intermediate asymptotics. Cambridge Texts in Applied Mathematics. Cambridge University Press, Cambridge, 1996.

Nonlocal (local) nonlinear diffusion

Let $Q_T := \mathbb{R}^N \times (0, T)$. We consider the following Cauchy problem:

(GPME)
$$\begin{cases} \partial_t u = \mathcal{L}[\varphi(u)] & \text{in } Q_T, \\ u(x,0) = u_0(x) & \text{on } \mathbb{R}^N, \end{cases}$$

where

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$$\begin{aligned} \mathcal{L}[\psi] &= \mathcal{L}^{\sigma}[\psi] + \mathcal{L}^{\mu}[\psi] \\ &= \mathsf{local} + \mathsf{nonlocal} \quad \mathsf{(self-adjoint)} \end{aligned}$$

- $\varphi:\mathbb{R}\to\mathbb{R}$ is continuous and nondecreasing, and
- *u*₀ some rough initial data.

Main results:

- Uniqueness for $u_0 \in L^1 \cap L^\infty$.
- Convergent numerical schemes in $C([0, T]; L^1_{loc}(\mathbb{R}^N))$ for $u_0 \in L^1 \cap L^\infty$.

The assumption

 $(\mathsf{A}_{\varphi}) \qquad \varphi: \mathbb{R} \to \mathbb{R} \text{ is continuous and nondecreasing},$

includes nonlinearities of the following kind

- linear,
- the porous medium $\varphi(u) = u^m$ with m > 1,
- fast diffusion $\varphi(u) = u^m$ with 0 < m < 1, and
- (one-phase) Stefan problem $\varphi(u) = \max\{0, u c\}$ with c > 0.

Assumptions

The assumption

$$\begin{array}{l} (\mathsf{A}_{\mu}) \hspace{0.2cm} \mu \geq 0 \hspace{0.1cm} \text{is a symmetric Radon measure on} \hspace{0.1cm} \mathbb{R}^{N} \setminus \{0\} \hspace{0.1cm} \text{satisfying} \\ \\ \hspace{0.2cm} \int_{|z| \leq 1} |z|^2 \hspace{0.1cm} \mathrm{d}\mu(z) + \int_{|z| > 1} 1 \hspace{0.1cm} \mathrm{d}\mu(z) < \infty. \end{array}$$

ensures that our \mathcal{L}^{μ} includes important examples:

- the fractional Laplacian $-(-\Delta)^{\frac{\alpha}{2}}$ with $\alpha \in (0,2)$;
- the anisotropic fractional Laplacian $-\sum_{i=1}^{N} (-\partial_{x_i x_i}^2)^{\frac{\alpha_i}{2}}$ with $\alpha_i \in (0, 2)$;
- relativistic Schrödinger type operators $m^{\alpha}I (m^2I \Delta)^{\frac{\alpha}{2}}$ with $\alpha \in (0, 2)$ and m > 0;
- for the measure ν with $\nu(\mathbb{R}^N) < \infty$, $\mathcal{L}^{\nu}[\psi](x) = \int_{\mathbb{R}^N} (\psi(x+z) - \psi(x)) d\nu(z);$
- for the function J with $\int_{\mathbb{R}^d} J(z) \, dz = 1$, $\mathcal{L}^{J \, dz}[\psi] = J * \psi \psi$;
- Fourier multipliers $\mathcal{F}(\mathcal{L}^{\mu}[\psi]) = -s_{\mathcal{L}^{\mu}}\mathcal{F}(\psi)$.

Theorem

A linear, self-adjoint operator which is translation invariant and satisfies the global comparison principle is of the form $\mathcal{L} = \mathcal{L}^{\sigma} + \mathcal{L}^{\mu}$ where

$$\mathcal{L}^{\sigma}[\psi(x)] := \operatorname{tr}(\sigma \sigma^{T} D^{2} \psi(x))$$

$$\mathcal{L}^{\mu}[\psi(x)] := \mathsf{P.V.} \int_{|z|>0} \left(\psi(x+z) - \psi(x)\right) \mathrm{d}\mu(z)$$

Here, $\sigma \in \mathbb{R}^{N \times p}$ and $\mu \ge 0$ is a symmetric Radon measure satisfying

$$\int \min\{|z|^2,1\} \mathrm{d}\mu(z) < \infty.$$

P. COURRÈGE. Sur la forme intégro-différentielle des opérateurs de C_k^{∞} dans C satisfaisant au principe du maximum. Séminaire Brelot-Choquet-Deny. Théorie du Potentiel, 10(1):1–38, 1965–1966.

Local case: $\partial_t u = \Delta u$, $\partial_t u = \Delta u^m$, $\partial_t u = \Delta \varphi(u)$.

• Well-posedness:

J. L. VÁZQUEZ. *The porous medium equation. Mathematical theory.* Oxford Mathematical Monographs. The Clarendon Press, Oxford University Press, Oxford, 2007.

• Numerical results: Risebro, Karlsen, Bürger, DiBendedetto, Droniou, Eymard, Gallouet, Ebmeyer,...

Selective summary of previous results

Nonlocal case: $\partial_t u = \mathcal{L}^{\mu}[\varphi(u)].$

• Well-posedness when $\mathcal{L}^{\mu} \sim -(-\Delta)^{rac{lpha}{2}}$:

Many people: Vázquez, de Pablo, Quirós, Rodríguez, Brändle, Bonforte, Stan, del Teso, Muratori, Grillo, Punzo, ...

• Numerical results:

Finite-difference discretizations of the singular integral:

E. R. JAKOBSEN, K. H. KARLSEN, AND C. LA CHIOMA. Error estimates for approximate solutions to Bellman equations associated with controlled jump-diffusions. *Numer. Math.*, 110(2):221-255, 2008.



J. DRONIOU. A numerical method for fractal conservation laws. *Math. Comp.*, 79(269):95–124, 2010.



S. CIFANI AND E. R. JAKOBSEN. Entropy solution theory for fractional degenerate convection-diffusion equations. Ann. Inst. H. Poincaré Anal. Non Linéaire, 28(3):413–441, 2011.



Y. HUANG AND A. OBERMAN. Numerical methods for the fractional Laplacian: a finite difference–quadrature approach. *SIAM J. Numer. Anal.*, 52(6):3056–3084, 2014.

Powers of the discrete Laplacian:



O. CIAURRI, L. RONCAL, P. R. STINGA, J. L. TORREA, AND J. L. VARONA. Nonlocal discrete diffusion equations and the fractional discrete Laplacian, regularity and applications. *Adv. Math.*, 330:688–738, 2018.

Theorem (Uniqueness, [del Teso & JE & Jakobsen, 2017])

Assume (A_{φ}) , (A_{μ}) , and $u_0 \in L^1 \cap L^{\infty}(\mathbb{R}^N)$. Then there is at most one distributional/very weak solution $u \in L^1 \cap L^{\infty}(Q_T)$ of (GPME).

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Numerical schemes for (GPME)

Recall that our Cauchy problem was given as

(GPME)
$$\begin{cases} \partial_t u = \mathcal{L}[\varphi(u)] & \text{in } Q_T = \mathbb{R}^N \times (0, T), \\ u(x, 0) = u_0(x) & \text{on } \mathbb{R}^N. \end{cases}$$

Corresponding numerical scheme (NM):

$$\begin{cases} \frac{U_{\beta}^{j}-U_{\beta}^{j-1}}{\Delta t} = \mathcal{L}^{\nu_{h,1}}[\varphi(U_{\beta}^{j})] + \mathcal{L}^{\nu_{h,2}}[\varphi^{h}(U_{\beta}^{j-1})] & \text{in} \quad h\mathbb{Z}^{N} \times \Delta t\mathbb{N}, \\ "U_{\beta}^{0} = u_{0}" & \text{in} \quad h\mathbb{Z}^{N}, \end{cases}$$

where

$$\begin{aligned} \mathcal{L}^{\nu_{h,1}} + \mathcal{L}^{\nu_{h,2}} &\approx \mathcal{L} = \mathcal{L}^{\sigma} + \mathcal{L}^{\mu} \\ \varphi^{h} &\approx \varphi \end{aligned}$$

Note that

• in the nonlinear case, we can no longer expect smooth solutions!

Our framework includes

- a mixture of implicit and explicit schemes (*θ*-methods);
- the possibility of discretizing the singluar and nonsingular parts of \mathcal{L}^{μ} in different ways; and
- combinations of the above.

Also:

Explicit methods only works for Lipschitz φ because of CFL. But, instead of doing implicit methods for "demanding" φ , we can do less costly explicit methods with approximating φ .

Theorem (Convergence, [del Teso & JE & Jakobsen, 2018/2019]) For the interpolant U_{h} , we have

$$U_h \to u$$
 in $C([0, T]; L^1_{loc}(\mathbb{R}^N))$ as $h \to 0^-$

where $u \in L^1(Q_T) \cap L^{\infty}(Q_T) \cap C([0, T]; L^1_{loc}(\mathbb{R}^N))$ is a distributional solution of (GPME).

Note that we only assume $u_0 \in L^1 \cap L^\infty$.

Finite-difference discretizations: nonlocal

Let us for simplicity study

(FHE)
$$\begin{cases} \partial_t u = \mathcal{L}^{\mu}[u] & \text{in } \mathbb{R} \times (0, T), \\ u(x, 0) = u_0(x) & \text{on } \mathbb{R}. \end{cases}$$

Let us try to deduce that

$$\begin{split} \mathcal{L}^{h}[\psi](x) &:= \sum_{\mathbb{Z} \ni \beta \neq 0} \left(\psi(x + h\beta) - \psi(x) \right) \omega_{\beta,h} \\ &\approx \mathsf{P.V.} \int_{|z| > 0} \left(\psi(x + z) - \psi(x) \right) \mathrm{d}\mu(z) = \mathcal{L}^{\mu}[\psi] \end{split}$$

where $\omega_{\beta} = \omega_{-\beta} \ge 0$.

In a similar way,

$$\Delta_h[\psi](x) := \left(\psi(x-h) - \psi(x)\right) \frac{1}{h^2} + \left(\psi(x+h) - \psi(x)\right) \frac{1}{h^2} \approx \Delta[\psi](x).$$

Finite-difference discretizations: nonlocal

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$$\begin{cases} \partial_t u = \mathcal{L}^{\mu}[u] & \text{in } \mathbb{R} \times (0, T), \\ u(x, 0) = u_0(x) & \text{on } \mathbb{R}. \end{cases}$$

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$$\mathcal{L}^{h}[\psi](x) := \sum_{\mathbb{Z} \ni \beta \neq 0} \left(\psi(x + h\beta) - \psi(x) \right) \omega_{\beta,h}$$
$$\approx \mathsf{P.V.} \int_{|z| > 0} \left(\psi(x + z) - \psi(x) \right) \mathrm{d}\mu(z) = \mathcal{L}^{\mu}[\psi]$$

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In a similar way,

$$\Delta_h[\psi](x) := \left(\psi(x-h) - \psi(x)\right) \frac{1}{h^2} + \left(\psi(x+h) - \psi(x)\right) \frac{1}{h^2} \approx \Delta[\psi](x).$$

Finite-difference discretizations: nonlocal

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$$\begin{cases} \partial_t u = \mathcal{L}^{\mu}[u] & \text{in } \mathbb{R} \times (0, T), \\ u(x, 0) = u_0(x) & \text{on } \mathbb{R}. \end{cases}$$

Let us try to deduce that

$$egin{aligned} \mathcal{L}^h[\psi](x) &:= \sum_{\mathbb{Z}
i eta eta
eq 0} ig(\psi(x+heta) - \psi(x)ig) \omega_{eta,h} \ &pprox \mathsf{P.V.} \int_{|z|>0} ig(\psi(x+z) - \psi(x)ig) \,\mathrm{d}\mu(z) = \mathcal{L}^\mu[\psi] \end{aligned}$$

where $\omega_{\beta} = \omega_{-\beta} \ge 0$. Recall what we did with the long-jump random walk.

In a similar way,

$$\mathcal{L}^{h}[\psi](x) \supset \Delta_{h}[\psi](x) := \sum_{\{-1,1\} \ni \beta \neq 0} \left(\psi(x+h\beta) - \psi(x)\right) \frac{1}{h^{2}} \approx \Delta[\psi](x).$$

Advantage using general nonlocal framework

Keep in mind the following formula:

$$\mathcal{L}^h[\psi](x) = \sum_{\mathbb{Z}
i eta eta
eq 0} ig(\psi(x+heta) - \psi(x)ig) \omega_{eta,h}.$$

Now, note that

$$\sum_{\mathbb{Z}\ni\beta\neq 0} \left(\psi(x+h\beta)-\psi(x)\right)\omega_{\beta,h} = \int_{|z|>0} \left(\psi(x+z)-\psi(x)\right) \mathrm{d}\nu_h(z)$$

where $d\nu_h(z) = \sum_{\mathbb{Z} \ni \beta \neq 0} \omega_{\beta,h} d\delta_{h\beta}(z)$.

This includes the local discretization by simply choosing

$$\omega_{eta,h} = egin{cases} rac{1}{h^2} & ext{when } eta = \{-1,1\}, \ 0 & ext{otherwise.} \end{cases}$$

Proof of convergence

1. Since the operator and the nonlinearity are x-independent, the numerical scheme can be written, for $x \in \mathbb{R}^N$, as

$$U^{j}(x) - \Delta t \mathcal{L}^{\nu_{h,1}}[\varphi(U^{j})](x) = U^{j-1}(x) + \Delta t \mathcal{L}^{\nu_{h,2}}[\varphi^{h}(U^{j-1})](x).$$

2. At every time step, we have a combination of explicit and implicit steps:

(EP)
$$w - \Delta t \mathcal{L}^{\nu_{h,1}}[\varphi(w)] = f$$
 on \mathbb{R}^N ,

where $U^{j} = w = T_{imp}[f]$ and

$$f(x) = T_{\exp}[U^{j-1}](x) = U^{j-1}(x) + \Delta t \mathcal{L}^{\nu_{h,2}}[\varphi^h(U^{j-1})](x).$$

- 3. Well-posedness of (NM) \iff Well-posedness of (EP) and properties of T_{exp} .
- 4. To study T_{exp} , the CFL-condition comes naturally

 $\Delta t L_{arphi^h}
u_{h,2}(\mathbb{R}^N) \leq 1$ "time derivative \sim spatial derivatives"

- 5. Both operators T_{imp} and T_{exp} are "well-posed" in $L^1 \cap L^\infty$ and enjoy
 - comparison principle;
 - L¹-contraction; and
 - L^1/L^∞ -bounds.
- 6. All properties then carries over to the numerical scheme (NM).
- 7. In particular, we have for the interpolant U_h

$$\sup_{h} \|U_{h}(\cdot+\xi,t)-U_{h}(\cdot,t)\|_{L^{1}(\mathbb{R}^{N})} \leq \lambda(|\xi|)$$

$$\sup_{h} \|U_{h}(\cdot,t)-U_{h}(\cdot,s)\|_{L^{1}(\mathcal{K})} \leq \lambda(|t-s|).$$

- 8. An application of the Arzelà-Ascoli and Kolmogorov-Riesz compactness theorems then gives the desired compactness and convergence in $C([0, T]; L^1_{loc}(\mathbb{R}^N))$. Check that the limit of the numerical solution is indeed a distributional solution.
- 9. And then all the properties carries over to distributional solutions of (GPME).

Error plot for the fractional heat equation with lpha=1



Comments: • We do the simulations with "classical" solutions, so we basically test the consistency error of the operator.

• The MpR behaves better in practise $O(h^2)$ than in theory O(h).

The fractional (one-phase) Stefan problem with $\alpha = 1$: plot



Comments: • $\varphi(u) = \max\{0, u - 0.5\}.$ • $\varphi(u)$ is only Lipschitz even if u is smooth!

The fractional (one-phase) Stefan problem: error with MpR



Comments: • Recall that "Error" $\sim h + h^{2-\alpha}$.

• Since pointwise values did not make sense, the error is more stable in L^1 .

• 2D (one-phase) Stefan problem with $\varphi(u) = \max\{0, u-1\}$. Explicit method. $\mathcal{L} = ((\frac{1}{2}, \frac{47}{100}) \cdot D)^2 + (-\partial_{xx}^2)^{\frac{1}{4}}$.

Thank you for your attention!